

# Uncertainty reduction in (static) robust optimization

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# Decision dependent uncertainty in RO

- Consider the classical (static) robust optimization problem

$$\min_{\mathbf{y} \in \mathcal{Y} \subseteq \mathbb{R}_+^{n_y}} \max_{\boldsymbol{\xi} \in \Xi} (\mathbf{f} + \mathbf{F}\boldsymbol{\xi})^\top \mathbf{y} \quad (\text{RO})$$

where  $\mathcal{Y}$  is linearly constrained and  $\Xi = \{\boldsymbol{\xi} \in \mathbb{R}_+^{n_\xi} \mid \mathbf{D}\boldsymbol{\xi} \leq \mathbf{b}\}$  is compact.

## Remark

- (RO) can be reformulated as a deterministic equivalent problem by adding a polynomial number of variables and constraints.
- (RO) does not model interactions between the decision maker and uncertain parameters.

# Decision dependent uncertainty in RO

- RO with affine decision dependence is written as

$$\min_{\mathbf{x} \in \mathcal{X} \subseteq \mathbb{R}_+^{n_x}, \mathbf{y} \in \mathcal{Y} \subseteq \mathbb{R}_+^{n_y}} \mathbf{c}^\top \mathbf{x} + \max_{\boldsymbol{\xi} \in \Xi^{\text{AFF}}(\mathbf{x})} (\mathbf{f} + \mathbf{F}\boldsymbol{\xi})^\top \mathbf{y}$$

where  $\Xi^{\text{AFF}}(\mathbf{x}) = \{\boldsymbol{\xi} \in \mathbb{R}_+^{n_\xi} \mid \mathbf{D}\boldsymbol{\xi} \leq \mathbf{b} + \boldsymbol{\Delta}\mathbf{x}\}$  and  $\boldsymbol{\Delta} \in \mathbb{R}^{m_\xi \times n_x}$ .

## Remark

- This problem arises from different application contexts.
- It can also be a useful modelling tool.

## Theorem (Nohadani and Sharma (2018))

Robust optimization with affine decision dependence is NP-Hard.

# Uncertainty reduction in RO

- One particular affine decision dependence model is *uncertainty reduction*.
- We write (with  $\mathbf{v}, \mathbf{w} \in \mathbb{R}_+^{n_\xi}$ )

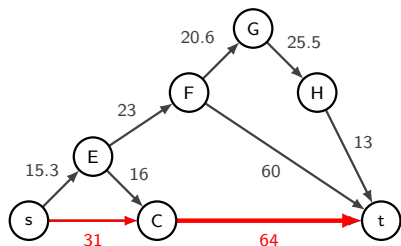
$$\Xi^{\text{UR}}(\mathbf{x}) = \{\boldsymbol{\xi} \in \mathbb{R}_+^{n_\xi} \mid \mathbf{D}\boldsymbol{\xi} \leq \mathbf{b}, \boldsymbol{\xi} \leq \mathbf{v} + \mathbf{w} \circ (\mathbf{1} - \mathbf{x})\}.$$

- Motivation: repair, investment, market studies, etc.
- Reduction is all-or-nothing, *i.e.*,  $\mathbf{x} \in \{0, 1\}^{n_\xi}$ .

## Remark

If  $v_i = 0$  then  $x_i = 1$  will completely reduce  $\xi_i$ , *i.e.*,  $\xi_i = 0$ .

# Example: shortest path problem <sup>1</sup>

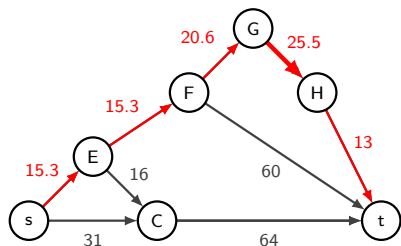


	Path s-C-t	Nominal	Worst-case
Nominal		95	127

- $\mathcal{Y}$  contains the flow constraints.
- $f_e = \bar{f}_e(1 + 0.5\xi_e)$ .
- $\Xi(\mathbf{x}) = \{\boldsymbol{\xi} \in \mathbb{R}_+^{|E|} \mid \sum_{e \in E} \xi_e \leq 1, \xi_e \leq 1 - 0.8x_e \quad \forall e \in E\}$ .
- $\mathcal{X} = \{\mathbf{x} \in \{0, 1\}^{|E|} \mid \sum_{e \in E} x_e \leq 1\}$ .

<sup>1</sup>from Nohadani and Sharma (2018)

# Example: shortest path problem <sup>1</sup>

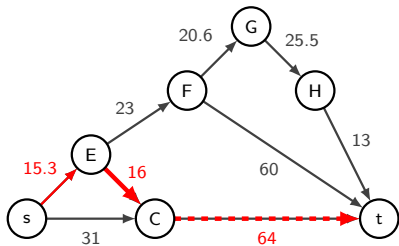


	Path	Nominal	Worst-case
Nominal	s-C-t	95	127
Robust	s-E-F-G-H-t	97.4	110.15

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# Example: shortest path problem <sup>1</sup>



	Path	Nominal	Worst-case
Nominal	s-C-t	95	127
Robust	s-E-F-G-H-t	97.4	110.15
UR Robust	s-E-C-t	95.3	108.1

- $\mathcal{Y}$  contains the flow constraints.
- $f_e = \bar{f}_e(1 + 0.5\xi_e)$ .
- $\Xi(\mathbf{x}) = \{\boldsymbol{\xi} \in \mathbb{R}_+^{|E|} \mid \sum_{e \in E} \xi_e \leq 1, \xi_e \leq 1 - 0.8x_e \quad \forall e \in E\}$ .
- $\mathcal{X} = \{\mathbf{x} \in \{0, 1\}^{|E|} \mid \sum_{e \in E} x_e \leq 1\}$ .

<sup>1</sup>from Nohadani and Sharma (2018)

# Decision dependence in the literature

- General models:
  - Nohadani and Sharma (2018)
  - Zeng and Wang (2022)
- As a modeling tool:
  - Spacey et al. (2012)
  - Poss (2013), Poss (2014)
  - Hanasusanto et al. (2015)

## Remark

Static robust optimization problems with decision-dependent uncertainty sets have close connections to bilevel programming and generalized semi-infinite programming.



# Uncertainty reduction in robust combinatorial optimization

- In this talk, we will be interested in problems of the form:

$$\begin{aligned} \min_{\mathbf{x} \in \mathcal{X} \subseteq \{0,1\}^n, \mathbf{y} \in \mathcal{Y} \subseteq \{0,1\}^n} \quad & \mathbf{c}^\top \mathbf{x} + \max_{\boldsymbol{\xi} \in \mathbb{R}_+^n} (\mathbf{f} + \mathbf{F}\boldsymbol{\xi})^\top \mathbf{y} \quad (\text{UR-Min-Max}) \\ \text{s.t.} \quad & \mathbf{d}^\top \boldsymbol{\xi} \leq b \\ & \boldsymbol{\xi} \leq \mathbf{v} + \mathbf{w} \circ (\mathbf{1} - \mathbf{x}) \end{aligned}$$

with  $\mathbf{F}$  a diagonal matrix.

## Remark

We assume that uncertainty is only present in the objective function and the uncertainty set has a single “complicating” constraint for ease of exposition.

# Uncertainty reduction in robust combinatorial optimization

- In this talk, we will be interested in problems of the form:

$$\begin{aligned} \min_{\mathbf{x} \in \mathcal{X} \subseteq \{0,1\}^n, \mathbf{y} \in \mathcal{Y} \subseteq \{0,1\}^n} \quad & \mathbf{c}^\top \mathbf{x} + \max_{\boldsymbol{\xi} \in \mathbb{R}_+^n} (\mathbf{f} + \mathbf{F}\boldsymbol{\xi})^\top \mathbf{y} \quad (\text{UR-Min-Max}) \\ \text{s.t.} \quad & \mathbf{d}^\top \boldsymbol{\xi} \leq b \\ & \boldsymbol{\xi} \leq \mathbf{v} + \mathbf{w} \circ (\mathbf{1} - \mathbf{x}) \end{aligned}$$

with  $\mathbf{F}$  a diagonal matrix.

## Remark

- (UR-Min-Max) is NP-Hard even when the underlying combinatorial problem is polynomially solvable.
- This is in contrast to robust combinatorial optimization problems without decision dependence.

# An algorithmic approach

## Proposition

(UR-Min-Max) *can be solved as at most  $n + 1$  deterministic (bilinear) problems in the  $\mathcal{X} \times \mathcal{Y}$  space.*

## Proof.

- Assuming  $\mathbf{v} = \mathbf{0}$  and  $\mathbf{F} = \mathbf{I}$  for ease of exposition:

$$\min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + \max_{\boldsymbol{\xi} \in \mathbb{R}_+^n} \boldsymbol{\xi}^\top \mathbf{y} \quad (\text{UR-Min-Max})$$

$$\text{s.t.} \quad \sum_{j \in [n]} d_j \xi_j \leq b \quad (\theta)$$

$$\xi_j \leq w_j(1 - x_j) \quad \forall j \in [n] \quad (\pi)$$

# An algorithmic approach

Proof.

- Through LP duality:

$$\min_{\substack{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y} \\ \theta \in \mathbb{R}_+, \boldsymbol{\pi} \in \mathbb{R}_+^n}} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + b\theta + \sum_{j \in [n]} w_j(1 - x_j)\pi_j$$

$$\text{s.t. } d_j\theta + \pi_j \geq y_j \quad \forall j \in [n].$$

- In any optimal solution, given  $\mathbf{x}, \mathbf{y}, \theta$ , we have that:

$$\pi_j^* = [y_j - d_j\theta]^+ \quad \forall j \in [n]$$

where  $[a]^+ := \max\{a, 0\}$ .

# An algorithmic approach

Proof.

$$\min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}, \theta \in \mathbb{R}_+} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + b\theta + \sum_{j \in [n]} w_j (1 - x_j) [y_j - d_j \theta]^+$$

- The maximum function is convex but nonlinear in  $\mathbf{y}$ .
- Since  $\mathcal{Y} \subseteq \{0, 1\}^n$ , we have for  $j \in [n]$ :

$$y_j = 1 \implies [y_j - d_j \theta]^+ = [1 - d_j \theta]^+$$

$$y_j = 0 \implies [y_j - d_j \theta]^+ = [-d_j \theta]^+$$

- We then obtain the linear expression in  $\mathbf{y}$ :

$$[y_j - d_j \theta]^+ = [1 - d_j \theta]^+ y_j + [-d_j \theta]^+ (1 - y_j) \quad \forall j \in [n]$$

# An algorithmic approach

Proof.

- Substituting, we obtain:

$$\min_{\substack{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y} \\ \theta \in \mathbb{R}_+}} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + b\theta \\ + \sum_{j \in [n]} w_j (1 - x_j) \left( [1 - d_j \theta]^+ y_j + [-d_j \theta]^+ (1 - y_j) \right).$$

Remark

For fixed  $\mathbf{x}, \mathbf{y}$ , the problem can be stated as minimizing a positive-weighted combination of piecewise affine convex functions of  $\theta \in \mathbb{R}_+$ .

# An algorithmic approach

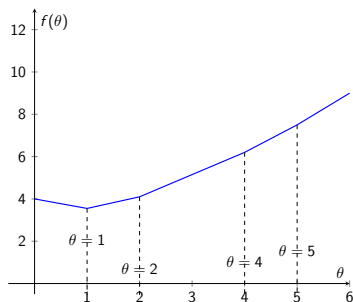


Figure:  $f(\theta) = 1.5\theta + [1 - \theta]^+ + [1 - 0.5\theta]^+ + [1 - 0.25\theta]^+ + [1 - 0.2\theta]^+$

## Remark

An optimal solution is obtained as one of the breakpoints of the individual functions:  $\theta = \frac{1}{d_j}$  for  $[1 - d_j\theta]^+$  when  $d_j > 0$  and  $\theta = 0$  for  $[-d_j\theta]^+$ .

# An algorithmic approach

Proof.

- In the worst case  $d_j > 0$  for  $j \in [n]$ .
- Therefore  $\theta^* \in \{0, \frac{1}{d_1}, \dots, \frac{1}{d_n}\}$ .
- (UR-Min-Max) can be solved as  $n + 1$  problems:

$$b\bar{\theta} + \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + \sum_{j \in [n]} w_j (1 - x_j) ([1 - d_j \bar{\theta}]^+ y_j + [-d_j \bar{\theta}]^+ (1 - y_j)).$$

each time fixing  $\bar{\theta} = \frac{1}{d_j}$  for  $j = 1, \dots, n$  with  $d_j > 0$  (plus  $\bar{\theta} = 0$ ).



# An algorithmic approach

- This approach works for:
  - any  $\mathbf{v} \geq 0$  and any diagonal matrix  $\mathbf{F}$
  - any polyhedral uncertainty set (with multiple “complicating constraints”)
  - multiple constraints affected by uncertainty (and not just the objective function)

## Attention!

In the last two cases the number of deterministic problems that needs to be solved increases exponentially in the number of constraints.

## So how do we solve this?

$$b\bar{\theta} + \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + \sum_{j \in [n]} w_j (1 - x_j) ([1 - d_j \bar{\theta}]^+ y_j + [-d_j \bar{\theta}]^+ (1 - y_j)).$$

### Remark

- Despite only involving  $\mathbf{x}$  and  $\mathbf{y}$  this problem has bilinear terms.
- The bilinear terms can be linearized using the McCormick envelope.
- We will show two cases in which this problem can be solved in polynomial time.

# Solution as a combinatorial problem

## Corollary

If  $\mathcal{X} = \{0, 1\}^n$ , an optimal solution of (UR-Min-Max) can be obtained by solving at most  $n + 1$  deterministic problems of the same form as:

$$\min_{\mathbf{y} \in \mathcal{Y}} \tilde{\mathbf{f}}^T \mathbf{y}. \quad (\text{Combinatorial})$$

## Remark

If (Combinatorial) is polynomially solvable for all  $\tilde{\mathbf{f}} \in \mathbb{R}^n$  then (UR-Min-Max) is polynomially solvable.

# Solution as a combinatorial problem

Proof.

- For given  $\bar{\theta}$ , we need to solve:

$$b\bar{\theta} + \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + \sum_{j \in [n]} w_j (1 - x_j) ([1 - d_j \bar{\theta}]^+ y_j + [-d_j \bar{\theta}]^+ (1 - y_j)).$$

- By rearranging the terms, we obtain:

$$K(\bar{\theta}) + \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{f}^\top \mathbf{y} + \sum_{j \in [n]} w_j ([1 - d_j \bar{\theta}]^+ - [-d_j \bar{\theta}]^+) y_j + \mathbf{c}^\top \mathbf{x} - \sum_{j \in [n]} w_j x_j ([1 - d_j \bar{\theta}]^+ y_j + [-d_j \bar{\theta}]^+ (1 - y_j)).$$

# Solution as a combinatorial problem

Proof.

- We write as:

$$K(\bar{\theta}) + \min_{\mathbf{y} \in \mathcal{Y}} \left\{ \mathbf{f}^\top \mathbf{y} + \sum_{j \in [n]} w_j ([1 - d_j \bar{\theta}]^+ - [-d_j \bar{\theta}]^+) y_j \right. \\ \left. + \min_{\mathbf{x} \in \mathcal{X}} \mathbf{c}^\top \mathbf{x} - \sum_{j \in [n]} w_j x_j ([1 - d_j \bar{\theta}]^+ y_j + [-d_j \bar{\theta}]^+ (1 - y_j)) \right\}.$$

- If  $\bar{\mathbf{y}} \in \mathcal{Y}$  is fixed, the inner problem becomes:

$$\min_{\mathbf{x} \in \mathcal{X}} \mathbf{c}^\top \mathbf{x} - \sum_{j \in [n]} w_j x_j ([1 - d_j \bar{\theta}]^+ \bar{y}_j + [-d_j \bar{\theta}]^+ (1 - \bar{y}_j)).$$

## Solution as a combinatorial problem

Proof.

- Rearranging, we obtain:

$$\min_{\mathbf{x} \in \mathcal{X}} \sum_{j \in [n]} (c_j - w_j ([1 - d_j \bar{\theta}]^+ \bar{y}_j + [-d_j \bar{\theta}]^+ (1 - \bar{y}_j))) x_j.$$

- We remark that if  $\mathcal{X} = \{0, 1\}^n$  then:

$$\begin{aligned} & \min_{\mathbf{x} \in \{0,1\}^n} \sum_{j \in [n]} (c_j - w_j ([1 - d_j \bar{\theta}]^+ \bar{y}_j + [-d_j \bar{\theta}]^+ (1 - \bar{y}_j))) x_j \\ &= \sum_{j \in [n]} \min_{x_j \in \{0,1\}} (c_j - w_j ([1 - d_j \bar{\theta}]^+ \bar{y}_j + [-d_j \bar{\theta}]^+ (1 - \bar{y}_j))) x_j \end{aligned}$$

*i.e.*, the problem decomposes over  $\mathbf{x}$ .

## Solution as a combinatorial problem

Proof.

- We focus on the problem over each  $x_j \in \{0, 1\}$ .

$$z_j = \min_{x_j \in \{0,1\}} (c_j - w_j ([1 - d_j \bar{\theta}]^+ \bar{y}_j + [-d_j \bar{\theta}]^+ (1 - \bar{y}_j))) x_j$$

- Since  $\mathcal{Y} \subseteq \{0, 1\}^n$  and  $x_j \in \{0, 1\}$ , we have:

$$\bar{y}_j = 0 \implies z_j = [c_j - w_j [-d_j \bar{\theta}]^+]^-$$

$$\bar{y}_j = 1 \implies z_j = [c_j - w_j [1 - d_j \bar{\theta}]^+]^-$$

where  $[a]^- = \min\{0, a\}$ .

- We then obtain the linear expression in  $\bar{\mathbf{y}}$ :

$$z_j = [c_j - w_j [1 - d_j \bar{\theta}]^+]^- \bar{y}_j + [c_j - w_j [-d_j \bar{\theta}]^+]^- (1 - \bar{y}_j)$$

# Solution as a combinatorial problem

Proof.

- Putting it all together...
- Given  $\bar{\theta}$ , solve:

$$K'(\bar{\theta}) + \min_{\mathbf{y} \in \mathcal{Y}} \sum_{j \in [n]} (f_j + w_j[1 - d_j\bar{\theta}]^+ - w_j[-d_j\bar{\theta}]^+ \\ + [c_j - w_j[1 - d_j\bar{\theta}]^+]^- - [c_j - w_j[-d_j\bar{\theta}]^+]^-) y_j$$

- In other words, solve a problem of the form:

$$\min_{\mathbf{y} \in \mathcal{Y} \subseteq \{0,1\}^n} \tilde{\mathbf{f}}^\top \mathbf{y}$$

where  $\tilde{\mathbf{f}}$  is completely determined by data.





## Solution as a linear programming problem

- $\mathcal{X} = \{\mathbf{x} \in \{0, 1\}^n \mid \mathbf{A}^x \mathbf{x} \leq \mathbf{b}^x\}, \mathbf{A}^x \geq 0$
- $\mathcal{Y} = \{\mathbf{y} \in \{0, 1\}^n \mid \mathbf{A}^y \mathbf{y} \leq \mathbf{b}^y\}$

### Corollary

If  $\mathbf{c}, \mathbf{d} \geq 0$  and  $\mathbf{A}' := \begin{pmatrix} \mathbf{A}^x & 0 \\ 0 & \mathbf{A}^y \\ \mathbf{I} & -\mathbf{I} \end{pmatrix}$  is totally unimodular and  $\mathbf{b}^x, \mathbf{b}^y \in \mathbb{Z}$ , an optimal solution of (UR-Min-Max) can be obtained by solving at most  $n + 1$  linear programs with constraint matrix  $\mathbf{A}'$ .

# Solution as a linear programming problem

Proof.

- For given  $\bar{\theta}$ , we need to solve:

$$b\bar{\theta} + \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \mathbf{f}^\top \mathbf{y} + \sum_{j \in [n]} w_j (1 - x_j) ([1 - d_j \bar{\theta}]^+ y_j + [-d_j \bar{\theta}]^+ (1 - y_j)).$$

- Assuming  $\mathbf{d} \geq 0$ , and since  $\bar{\theta} \geq 0$ , we obtain:

$$b\bar{\theta} + \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \tilde{\mathbf{f}}(\bar{\theta})^\top \mathbf{y} - \sum_{j \in [n]} w_j [1 - d_j \bar{\theta}]^+ x_j y_j,$$

where  $\tilde{f}_j(\bar{\theta}) = f_j + w_j [1 - d_j \bar{\theta}]^+$  for  $j \in [n]$ .

# Solution as a linear programming problem

Proof.

$$b\bar{\theta} + \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \tilde{\mathbf{f}}(\bar{\theta})^\top \mathbf{y} - \sum_{j \in [n]} w_j [1 - d_j \bar{\theta}]^+ x_j y_j,$$

- Assuming  $\mathbf{c}, \mathbf{A}^\mathbf{x} \geq 0$ , we have that,  $\mathbf{x} \leq \mathbf{y}$  in any optimal solution.
- We may therefore write:

$$b\bar{\theta} + \min_{\substack{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y} \\ \mathbf{x} \leq \mathbf{y}}} \mathbf{c}^\top \mathbf{x} + \tilde{\mathbf{f}}(\bar{\theta})^\top \mathbf{y} - \sum_{j \in [n]} w_j [1 - d_j \bar{\theta}]^+ x_j y_j.$$

- Since  $\mathbf{x}, \mathbf{y} \in \{0, 1\}^n$  and  $\mathbf{x} \leq \mathbf{y}$ , we have:

$$x_j y_j = x_j \quad \forall j \in [n].$$

# Solution as a linear programming problem

Proof.

- Introducing  $\tilde{c}_j(\bar{\theta}) = c_j - w_j[1 - d_j\bar{\theta}]^+$  for each  $j \in [n]$ , we have:

$$\min \quad \tilde{\mathbf{c}}(\bar{\theta})^\top \mathbf{x} + \tilde{\mathbf{f}}(\bar{\theta})^\top \mathbf{y}$$

$$\text{s.t.} \quad \mathbf{A}^x \mathbf{x} \leq \mathbf{b}^x$$

$$\mathbf{A}^y \mathbf{y} \leq \mathbf{b}^y$$

$$\mathbf{x} - \mathbf{y} \leq \mathbf{0}$$

$$(\mathbf{x}, \mathbf{y}) \in \{0, 1\}^{2n}.$$



Remark

If the stated TU assumptions are satisfied then the above integer program can be solved as a linear program.

# MILP reformulations

- Let's come back to mathematical programming:

$$\begin{aligned} \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \max_{\boldsymbol{\xi} \in \mathbb{R}_+^n} (\mathbf{f} + \mathbf{F}\boldsymbol{\xi})^\top \mathbf{y} & \quad (\text{UR-Min-Max}) \\ \text{s.t.} \quad \mathbf{d}^\top \boldsymbol{\xi} \leq b & \quad (\sigma) \\ \boldsymbol{\xi} \leq \mathbf{v} + \mathbf{w} \circ (\mathbf{1} - \mathbf{x}) & \quad (\pi) \end{aligned}$$

- A monolithic bilinear formulation is obtained through LP duality.
- Will require linearizing the bilinear terms in  $\boldsymbol{\pi}\mathbf{x}$ .

## Idea

Transfer the decision-dependence to the objective function of the adversarial problem.

# MILP reformulations

## Idea

Consider the uncertainty set:

$$\bar{\Xi}(\mathbf{x}) = \{\xi^1, \xi^2 \in \mathbb{R}_+^n \mid \mathbf{d}^\top (\xi^1 + \xi^2) \leq b, \xi^1 \leq \mathbf{v}, \xi^2 \leq \mathbf{w} \circ (\mathbf{1} - \mathbf{x})\}.$$

## Observation

For any  $\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}$

$$\max_{\xi \in \bar{\Xi}^{\text{UR}}(\mathbf{x})} (\mathbf{F}\xi)^\top \mathbf{y} = \max_{\xi^1, \xi^2 \in \bar{\Xi}(\mathbf{x})} (\mathbf{F}(\xi^1 + \xi^2))^\top \mathbf{y}$$

## Remark

In  $\bar{\Xi}(\mathbf{x})$  we have that  $\xi_j^2 = 0$  when  $x_j = 1$ .

# MILP reformulations

Proposition (generalized from Nohadani and Sharma (2018))

$$\max_{\xi \in \Xi^{\text{UR}}(\mathbf{x})} (\mathbf{F}\xi)^{\top} \mathbf{y} = \max_{\xi^1, \xi^2 \in \Xi(\mathbf{0})} (\mathbf{F}(\xi^1 + \xi^2))^{\top} \mathbf{y} - (\bar{\mathbf{\Pi}}\mathbf{x})^{\top} \xi^2$$

where  $\bar{\mathbf{\Pi}}$  is a diagonal matrix with  $\pi_j^{\max}$  for  $j \in [n_{\xi}]$  on the diagonal.

Proposition (generalized from Nohadani and Sharma (2018))

If  $\mathbf{d} \geq 0$  then  $\pi_j^{\max}$  for  $j \in [n_{\xi}]$  can be set to  $\max\{0, \max_{\mathbf{y} \in \mathcal{Y}} (\mathbf{F}^{\top} \mathbf{y})^{\top} \mathbf{e}_j\}$ .

Remark

If  $\mathbf{F}$  is diagonal and  $\mathcal{Y} \subseteq \{0, 1\}^n$  then  $\bar{\mathbf{\Pi}} = \max\{0, \mathbf{F}\}$ .

# MILP reformulations

- When  $\mathbf{F} \geq 0$  and diagonal we obtain the reformulation:

$$\min_{\mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}} \mathbf{c}^\top \mathbf{x} + \max_{\boldsymbol{\xi}^1, \boldsymbol{\xi}^2 \in \mathbb{R}_+^n} \mathbf{y}^\top \mathbf{F} \boldsymbol{\xi}^1 + (\mathbf{y} - \mathbf{x})^\top \mathbf{F} \boldsymbol{\xi}^2 \quad (\text{UR-Min-Max})$$

$$\text{s.t.} \quad \mathbf{d}^\top (\boldsymbol{\xi}^1 + \boldsymbol{\xi}^2) \leq b \quad (\boldsymbol{\sigma})$$

$$\boldsymbol{\xi}^1 \leq \mathbf{v} \quad (\boldsymbol{\pi})$$

$$\boldsymbol{\xi}^2 \leq \mathbf{w} \quad (\boldsymbol{\mu})$$

- A monolithic deterministic formulation is obtained through LP duality.
- No bilinear terms!



## Results on the shortest path problem

$$\min_{\mathbf{x} \in \{0,1\}^{|A|}} \max_{\mathbf{y} \in \mathcal{Y}} \xi \in \Xi^{\text{SP}}(\mathbf{x}) \quad \mathbf{c}^T \mathbf{x} + (\bar{\mathbf{f}} + \frac{1}{2} \xi \circ \bar{\mathbf{f}})^T \mathbf{y}$$

$$\Xi^{\text{SP}}(\mathbf{x}) = \left\{ \xi \in \mathbb{R}_+^{|A|} \mid \sum_{(i,j) \in A} \xi_{ij} \leq \Gamma, \xi_{ij} \leq 1 - \gamma_{ij} x_{ij} \quad \forall (i,j) \in A \right\}.$$

- We compare the algorithmic approach to the MIP reformulation based on big-M.
- We use a commercial (Gurobi) and an open source solver (HiGHS).
- We use LightGraphs.jl to solve deterministic SPs for the algorithmic approach.

## Results on the shortest path problem

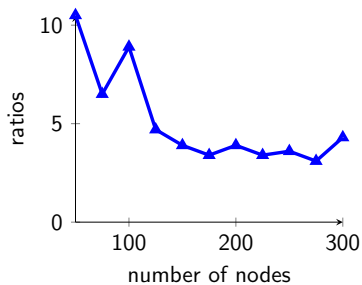


Figure: Geometric averages of the ratio between solution times using Gurobi.

- $n \in \{25, 50, \dots, 300\}$ , 10 randomly generated instances<sup>2</sup> in each group.
- $\bar{\mathbf{f}}$  euclidean,  $\mathbf{c} = \mathbf{1}$ ,  $\Gamma = 2$ ,  $\gamma = 0.2$ .
- Time limit of 2 hours.

<sup>2</sup>same generation procedure as in Nohadani and Sharma (2018)

## Results on the shortest path problem

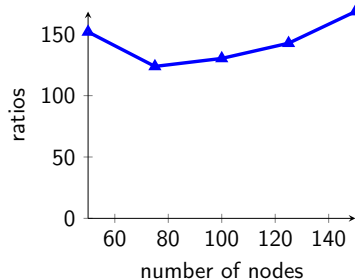


Figure: Geometric averages of the ratio between solution times using HiGHS.

- $n \in \{25, 50, \dots, 150\}$ , 10 randomly generated instances<sup>2</sup> in each group.
- $\bar{\mathbf{f}}$  euclidean,  $\mathbf{c} = \mathbf{1}$ ,  $\Gamma = 2$ ,  $\gamma = 0.2$ .
- Time limit of 2 hours.

<sup>2</sup>same generation procedure as in Nohadani and Sharma (2018)

# Conclusions

## take-away message

- Robust optimization with decision-dependent uncertainty sets is an interesting paradigm for many applications.
- It leads to difficult problems in general.
- Certain special cases remain polynomially solvable.

## future work

- Exploring further algorithmic approaches.
- More general uncertainty-dependence structures.
- Decision-dependent adjustable robust optimization problems.

*Thank you for your attention!*

Arslan, Ayşe N., and Michael Poss. "Uncertainty reduction in robust optimization." *Operations Research Letters* (2024): 107131.